

## Government Documents Admit Flat Earth

Russia 1948 Shape of the earth unknown.. <https://www.cia.gov/library/readingroom/docs/CIA-RDP80-00809A000600231031-1.pdf>

Russian Light Study “Brightness of the firmament” Flat earth :

[https://drive.google.com/file/d/1KX7\\_0tTAzFEWJ1CWOXQ\\_K2JnUgfbzb8/view](https://drive.google.com/file/d/1KX7_0tTAzFEWJ1CWOXQ_K2JnUgfbzb8/view)

Propagation of Electromagnetic Fields Over Flat Earth <http://www.arl.army.mil/arlreports/2001/ARL-TR-2352.pdf>

page 9: based upon the signal having a single bounce on a flat Earth

<http://www.arl.army.mil/arlreports/2009/ARL-TR-4998.pdf>

page 1: Trajectory of Spinning Projectiles: “These equations assume a flat Earth.”

<http://www.arl.army.mil/arlreports/2010/ARL-TR-5118.pdf>

page 2: “These equations assume a flat Earth..” <http://www.arl.army.mil/arlreports/2011/ARL-TR-5810.pdf>

page 216: "assuming a flat Earth" <http://tycho.usno.navy.mil/ptti/2007papers/paper21.pdf>

Page 1: “...so that a flat-earth approximation provides the best estimate.”

<http://www.arl.army.mil/arlreports/2001/ARL-TN-175.pdf>

Page 39: model works over a flat earth <http://www.arl.army.mil/arlreports/2003/ARL-TR-2696.pdf>

page 1: transmission loss over flat earth <http://www.arl.army.mil/arlreports/2000/ARL-TR-2156.pdf>

page 9: “...input to a flat earth” <http://www.arl.army.mil/arlreports/2003/ARL-MR-563.pdf>

page 3: “The first is the Earth-fixed coordinate system, which is fixed to the Earth with a flat Earth assumption.”

<http://www.arl.army.mil/arlreports/2010/ARL-CR-650.pdf>

page: 1 flat earth approximation provides the best estimate <http://www.arl.army.mil/arlreports/2002/ARL-TR-2683.pdf>

page 32: This model works well over a flat-earth <http://www.arl.army.mil/arlreports/2000/ARL-TR-1812.pdf>

page 168: equations of flat-earth trigonometry. [http://www.irig106.org/docs/106-17/106-17\\_Telemetry\\_Standards.pdf](http://www.irig106.org/docs/106-17/106-17_Telemetry_Standards.pdf)

page 8: The Earth is flat and nonrotating.

<http://www.navair.navy.mil/nawcwg/command/Inplace.aspx/LoadFile/531> General Equations of Motion for Damaged Asymmetric Aircraft

Page 1: "...equations of motions must properly reflect the underlying physics."

page 2: "In this paper, the rigid body equations of motion over a flat non-rotating earth are developed..."

<https://ntrs.nasa.gov/archive/nasa/casi.ntrs.nasa.gov/20070030307.pdf> Approximate Optimal Guidance for the Advanced Launch System On

page one this document does mention a spherical rotating earth but then staff DIFficult to prove" and 2) "...not suggested to be used as a basis for an online real-time guidance law."

Page 32 goes on to say: "Lastly, the equations of motion for the zeroth-order problem of flight in a vacuum over a flat Earth are presented." <https://ntrs.nasa.gov/archive/nasa/casi.ntrs.nasa.gov/19940020279.pdf> SR-71

Page 8 "...nonrotating Earth..." [https://www.nasa.gov/centers/dryden/pdf/88507main\\_H-2179.pdf](https://www.nasa.gov/centers/dryden/pdf/88507main_H-2179.pdf)

page 14: (2) A flat, nonrotating earth <https://ntrs.nasa.gov/archive/nasa/casi.ntrs.nasa.gov/19710018599.pdf>

page 8: the missile position in space is computed relative to a flat nonrotating earth.

<https://ntrs.nasa.gov/archive/nasa/casi.ntrs.nasa.gov/20040008097.pdf>

page 108: aircraft flying over flat, nonrotating earth page:12 "aircraft flying in a stationary atmosphere over flat nonrotating earth" [https://www.nasa.gov/centers/dryden/pdf/88072main\\_H-1259.pdf](https://www.nasa.gov/centers/dryden/pdf/88072main_H-1259.pdf)

NASA Technical Paper 2835 Page 1 Summary: Flat nonrotating earth page 126: "The nonlinear equations of motion used are six-degree-of-freedom equations sith stationary atmosphere and flat, nonrotating earth"

<https://ntrs.nasa.gov/archive/nasa/casi.ntrs.nasa.gov/19890007066.pdf>

Determination of Angles of Attack and Sideslip from Radar Data and a Roll Stabilized Platform NASA March 1972

page 2: "The method is limited, however, to application where a flat, nonrotating earth"

<https://ntrs.nasa.gov/archive/nasa/casi.ntrs.nasa.gov/19720012071.pdf> An Aircraft Model for the AIAA Controls Design Challenge NASA 1991

page 11: "The nonlinear equations of motion used in this model are general six-degree-of-freedom equations representing the flight dynamics of a rigid aircraft flying in a stationary atmosphere over a flat nonrotating earth"

[https://www.nasa.gov/centers/dryden/pdf/88248main\\_H-1777.pdf](https://www.nasa.gov/centers/dryden/pdf/88248main_H-1777.pdf) Investigation of Aircraft Landing in Variable Wind Fields NASA 1973

page14 pdf or 6 on actual report: a) The earth is flat and non-rotating.

<https://ntrs.nasa.gov/archive/nasa/casi.ntrs.nasa.gov/19790005472.pdf> A Mathematical Model of the CH-53

Helicopter NASA page 17: “The helicopter equations of motion are given in body axes with respect to a flat, nonrotating Earth.” <https://ntrs.nasa.gov/archive/nasa/casi.ntrs.nasa.gov/19810003557.pdf> Atmospheric Oscillations Georgia Tech April 1965 Prepared for NASA

page 13: A model frequently used is that of a flat, nonrotating earth.

<https://ntrs.nasa.gov/archive/nasa/casi.ntrs.nasa.gov/19650015408.pdf>

page 19: These equations assume a rigid vehicle and a flat, nonrotating Earth.

[https://www.nasa.gov/centers/dryden/pdf/88733main\\_H-2465.pdf](https://www.nasa.gov/centers/dryden/pdf/88733main_H-2465.pdf) Flight Testing a VSTOL Aircraft NASA 1988

page 9 pdf or 4-5 on actual doc: “For aircraft problems, the state and measurement models together represent the kinematics of a rigid body for describing motion over a flat, nonrotating Earth...”

<https://ntrs.nasa.gov/archive/nasa/casi.ntrs.nasa.gov/19880014378.pdf> Time to Climb

page2: “In our minimum time-to-climb problem, the aircraft is modeled as a point mass and the flight trajectory is strictly confined in a vertical plane on a non-rotating, flat earth.

<https://ntrs.nasa.gov/archive/nasa/casi.ntrs.nasa.gov/20060053337.pdf>